





Introduction

- In this topic, we will
 - Describe the representation of polynomials
 - Discuss the idea of evaluating polynomials
 - Look at a sequence of more efficient implementations
 - We will use C++
 - Describe the evaluation of polynomials in MATLAB





Representing a polynomial

• As with our representation, in C++, we will represent a polynomial as an array where a[k] is the coefficient of x^k

$$a_n x^n + a_{n-1} x^{n-1} + \dots + a_2 x^2 + a_1 x + a_0$$

– For example:

double a[3]{ 2.0, 3.0, 1.0 };
$$// x^2 + 3x + 2$$





Representing a polynomial

- In Matlab, a polynomial is represented with a vector:
 - An *n*-dimensional vector is polynomial of degree n-1
 - If p is an n-dimensional vector, p(k) is the coefficient of x^{n-k}
- Consequently, the following represents $x^2 + 3x + 2$

$$\Rightarrow$$
 p = [1 3 2];

 If a vector is passed to a function expecting a polynomial, the vector is interpreted as described above:

```
>> roots( p )
     ans =
     -2
     -1
```



This Matlab code is provided for demonstration purposes and is not required for the examination.





Representing a polynomial

Some other useful polynomial functions in Matlab:

```
>> polyder( [1 3 2] )  % take the derivative
    ans =
        2 3
>> polyint( [1 3 2] )  % find the antiderivative
    ans =
        0.3333  1.5000  2.0000  0
```







Suppose you have the polynomial

$$1.2 x^4 - 3.8 x^3 + 4.9 x^2 - 0.7 x + 5.6$$

- How would you evaluate this at x = 2.5?
- Author a function pow(double x, unsigned int n) and call it





• The most expensive way of calculating x^n :

```
template <typename T>
T pow_0_n(T x, int n) {
    if (n >= 0) {
                                                x^n = \underbrace{x \cdot x \cdot x \cdot x \cdot x}_{n \text{ time}}
          T result{ 1.0 };
          for ( int k{1}; k <= n; ++k ) {
               result *= x;
                                                                    O(n)
          return result;
     } else if ( n == INT_MIN ) {
          return pow 0 n( 1.0/x, -(n + 1) )/x;
                                                                    x^n = \left(\frac{1}{x}\right)^n
     } else {
          return pow_0_n( 1.0/x, -n );
```





The most expensive form:

```
template <typename T>
T polyval_0_n2( T coeffs[], unsigned int degree, T x ) {
    T result{ coeffs[0] };

    for ( unsigned int k{1}; k <= degree; ++k ) {
        result += coeffs[k]*pow_0_n( x, k );
    }

    return result;
}</pre>
```





A recursive means of calculating x^n : $x^n = \begin{cases} \left(\frac{n}{x^2}\right)^2 & n \text{ is even} \end{cases}$ template <typename T> T pow_0_ln_n_rec(T x, int n) { $\left[x\left(\frac{n-1}{x^2}\right)^2\right]$ n is odd if (n > 0) { T result{ pow_0_ln_n_rec(x, n/2) }; result *= result; return ((n&1) == 0) ? result : result*x; } else if (n == 0) { return 1.0; $O(\ln(n))$ } else if (n == INT_MIN) { return pow_0_ln_n_rec(1.0/x, -(n + 1))/x; } else { return pow 0 ln n rec(1.0/x, -n);





A more efficient approach:

```
template <typename T>
T polyval_O_n_ln_n_rec( T coeffs[], unsigned int degree, T x ) {
   T result{ coeffs[0] };
   for (unsigned int k{1}; k <= degree; ++k ) {
        result += coeffs[k]*pow_0_ln_n_rec( x, k );
                                                     O(n \ln(n))
    return result;
```





• An iterative means of calculating x^n :

```
template <typename T>
T pow_0_ln_n_iter( T x, int n ) {
    if (n >= 0)
        T result{ 1.0 };
                                           x^{21} = x^{16+4+1} = x^{16}x^4x^1
        for (; n > 0; n <<= 1, x *= x)
            if ( (n&1) == 1 ) {
                result *= x;
        return result;
    } else if ( n == INT MIN ) {
                                                         O(\ln(n))
        return pow_0_ln_n_iter( 1.0/x, -(n + 1) )/x;
    } else {
        return pow_0_ln_n_iter( 1.0/x, -n );
```





An even more efficient approach:

```
template <typename T>
T polyval_O_n( T coeffs[], unsigned int degree, T x ) {
   T result{ coeffs[0] };
   T term{ 1.0 };
                                                          O(n)
   for ( unsigned int k{1}; k <= degree; ++k ) {
       term *= x;
        result += coeffs[k]*term;
    return result;
```

- A total of approximately 3n FLOPs







All these evaluate the polynomial in the standard form

$$1.2 x^4 - 3.8 x^3 + 4.9 x^2 - 0.7 x + 5.6$$

— What about rewriting it?

$$(1.2 x - 3.8) x^3 + 4.9 x^2 - 0.7 x + 5.6$$

$$((1.2 x - 3.8) x + 4.9) x^2 - 0.7 x + 5.6$$

$$(((1.2 x - 3.8) x + 4.9) x - 0.7) x + 5.6$$

- This has only 2n FLOPs
- This is known as *Horner's rule* for evaluating polynomials





This has approximately half the run time of the previous version:

```
template <typename T>
T polyval_horner( T coeffs[], unsigned int degree, T x ) {
    T result{ coeffs[degree] };

    for ( unsigned int k{degree - 1}; k <= degree; --k ) {
        result = result*x + coeffs[k];
    }

    return result;
    O(n)
}</pre>
```





This implementation is approximately 1% faster:

```
template <typename T>
T polyval horner ptr( T coeffs[], unsigned int degree, T x ) {
    T *coeff{ coeffs + degree };
    T result{ *coeff };

    while (coeff > coeffs) {
        result = x*result + *--coeff;
    }

    return result;
}
```

If you require such efficiency, use assembly language...







Horner's rule

In Matlab, evaluating a polynomial is straight-forward:

```
>> p = [1 3 2];
>> polyval( p, 0.3 );  % calculate p(0.3)
    ans =
        2.9900
>> polyval( [1 3 2], [0.3 0.2; 0.5 -0.1] )
    ans =
        2.9900   2.6400
        3.7500   1.7100
```





Summary

- Following this topic, you now
 - Understand the representation of polynomials that:
 - We will use for C++
 - Is used in MATLAB
 - Have seen successively more efficient evaluations of polynomials
 - Are aware that this ends with the very efficient Horner's rule
 - Know that in MATLAB,
 calling polyval will evaluate the polynomial using Horner's rule





References

- [1] https://en.wikipedia.org/wiki/Horner%27s_method
- [2] https://www.mathworks.com/help/matlab/polynomials.html





Acknowledgments

None so far.





Colophon

These slides were prepared using the Cambria typeface. Mathematical equations use Times New Roman, and source code is presented using Consolas. Mathematical equations are prepared in MathType by Design Science, Inc. Examples may be formulated and checked using Maple by Maplesoft, Inc.

The photographs of flowers and a monarch butter appearing on the title slide and accenting the top of each other slide were taken at the Royal Botanical Gardens in October of 2017 by Douglas Wilhelm Harder. Please see

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